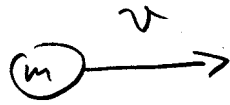


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$$m = 50g \quad v = 30 \text{ m/sec} \quad \Delta v = .001 v = 0.03 \text{ m/sec}$$

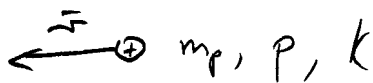
Uncertainty relation  $\Delta x \Delta p = \frac{\hbar}{2}$  minimum.

$$\Delta p = m \Delta v = .05 \text{ kg} \cdot 0.03 \frac{\text{m}}{\text{sec}} = 0.0015 \frac{\text{kg m}}{\text{sec}}$$

$$\Delta x = \frac{\hbar}{2 \Delta p} = \frac{1.055 \times 10^{-34} \text{ J-sec}}{2 (.0015 \frac{\text{kg m}}{\text{sec}})} = 3.52 \times 10^{-32} \text{ m. (1)}$$

They measuring that with a meterstick.

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$$m_p = 938.3 \frac{\text{MeV}}{c^2} \quad K = 1.0 \text{ MeV} \quad \Delta p = 5\%$$

Since  $K \ll m_p c^2$ , will use the classical form

$$K = \frac{p^2}{2m_p} \Rightarrow p = \sqrt{2m_p K} = 43.3 \frac{\text{MeV}}{c}$$

$$\Delta x \Delta p = \frac{\hbar}{2} \text{ minimum.}$$

$$\Delta x = \frac{\hbar}{2 \Delta p} = \frac{\hbar}{2 (.05) (43.3 \times 10^6 \frac{\text{eV}}{c})}$$

$$\Delta x = \frac{6.582 \times 10^{-16} \text{ eV-sec}}{4.33 \times 10^6 \frac{\text{eV}}{c}} = 4.56 \times 10^{-14} \text{ m}$$

↑ don't forget the c.

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Uncertainty principle:  $\Delta p \Delta x \geq \frac{h}{2}$

We have  $h = 2\pi \text{ J}\cdot\text{sec}$ , whence  $\frac{h}{2} = 1 \text{ J}\cdot\text{sec}$ .

Fuzzy has mass  $m = 2.0 \text{ kg}$  and the uncertainty in Fuzzy's position is  $\Delta x = 1.0 \text{ m}$ .

a) Set  $\Delta p \Delta x = \frac{h}{2}$ ; solve for  $\frac{\Delta p}{m}$

$$\Delta p = \frac{h}{2\Delta x} \Rightarrow \Delta v = \frac{h}{2\Delta x m}$$

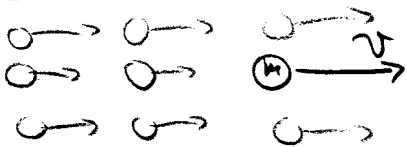
$$\Delta v = \frac{1 \text{ J}\cdot\text{sec}}{2 (1.0 \text{ m}) 2.0 \text{ kg}} = 0.25 \text{ m/sec}$$

b) At constant, but uncertain speed, Fuzzy's position becomes increasingly uncertain.

$$\begin{aligned} \text{After } 5.0 \text{ sec, } \Delta x &= \Delta x_0 + 5.0 \text{ sec} \times \Delta v \\ &= 1 \text{ m} + 5 \text{ sec} \cdot 0.25 \frac{\text{m}}{\text{sec}} \\ &= 2.25 \text{ m} \end{aligned}$$

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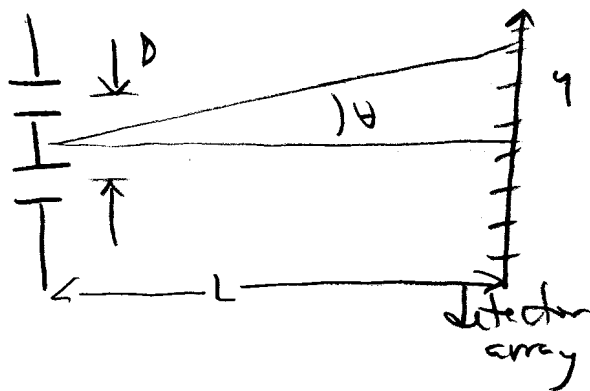


$$m = 939.6 \frac{\text{MeV}}{c^2}$$

$$v = 0.40 \text{ m/sec}$$

$$D = 1.0 \times 10^{-3} \text{ m}$$

$$L = 10 \text{ m}$$



Interference minima occur when  $D \sin \theta = m \frac{\lambda}{2}$ .

Since  $L \gg D$ , we'll say  $\sin \theta \approx \tan \theta$ .

$$D \frac{y_1}{L} = \frac{\lambda}{2} \Rightarrow y_1 = \frac{\lambda L}{2D}$$

$$a) \lambda = \frac{h}{p} = \frac{h}{mv} = \frac{4.136 \times 10^{-15} \text{ eV} \cdot \text{sec}}{939.6 \times 10^6 \frac{\text{eV}}{c^2} \cdot 0.40 \text{ m/sec}}$$

$$\lambda = 9.90 \times 10^{-7} \text{ m} = 990 \text{ nm}.$$

$$b) y_1 = \frac{\lambda L}{2D} = \frac{9.90 \times 10^{-7} \text{ m} \cdot 10 \text{ m}}{(2) 1.0 \times 10^{-3} \text{ m}} = 4.95 \times 10^{-3} \text{ m}.$$

c) Notice that  $\lambda \ll D$ . That's one way, crudely, to determine that we cannot tell which slit a neutron passed through.

See the fuller discussion on ~~(pp 177 and 178)~~  
(more careful)

pp 184-185 3rd ed.

5-31 3<sup>rd</sup> ed.

438 This one is a little tricky:

The particles are given a momentum along the x-axis. In passing through the hole of diameter  $d$ , we have an uncertainty of the particle's y-position of  $\Delta y = d$ .

Therefore there is an uncertainty in the particle's y-momentum.

$$\text{Roughly } \Delta p_y \cdot d = h.$$

If a particle has a non zero  $\Delta p_y$ , then sometime later, when it has travelled along the x-axis a distance  $x$ , the uncertainty in its y-coordinate will be  $\Delta y \propto \Delta p_y$ . What proportion?

It'll depend on the elapsed time, which in turn is related to  $x$  and  $p_x$ .

$$\text{So we'll say } \frac{x}{p_x} = \frac{\Delta y}{\Delta p_y}.$$

From above  $\Delta p_y = \frac{h}{d}$ , and solve for  $x$

$$x = p_x \frac{\Delta y d}{h} = \frac{10^{-3} \text{ kg } \frac{100 \text{ m}}{\text{sec}} \cdot 10^{-2} \text{ m} \cdot 2 \times 10^{-3} \text{ m}}{6.63 \times 10^{-34} \text{ J sec}}$$

$$x = 3 \times 10^{27} \text{ m}$$

- much greater than the given diameter of the universe